

Finite Differences

Consider the following ODE :

$$\left| \begin{array}{l} -p u''(x) + q u'(x) + r u(x) = f(x) \quad , \quad a < x < b \\ u(a) = g_a \\ u(b) = g_b \end{array} \right.$$

We wish to numerically approximate the solution u to this problem. The key mathematical tool we are going to use is Taylor's Theorem:

If $u : (a,b) \rightarrow \mathbb{R}$ has $k+1$ ^{continuous} derivatives at

$x \in (a,b)$, then for all sufficiently small h ,

$$u(x+h) = \underbrace{u(x) + u'(x)h + \frac{u''(x)h^2}{2} + \dots + \frac{u^{(k)}(x)h^k}{k!}}_{P_h(x)} + O(h^{k+1})$$

where the $O(h^{k+1})$ simply means that there is a constant C so

$$|u(x+h) - P_h(x)| \leq C h^{k+1} \quad \text{when } h \text{ is sufficiently small.}$$

How do we use this? We want to replace the derivatives in our PDE by certain differences involving $u(x+h)$ and $u(x)$ for small h . From Taylor's theorem with $k=1$, we have

$$u(x+h) = u(x) + u'(x)h + o(h^2) \rightarrow$$

$$\frac{u(x+h) - u(x)}{h} = u'(x) + o(h).$$

This can be interpreted as saying that we can replace $u'(x)$ by $\frac{u(x+h) - u(x)}{h}$ and we will introduce an error that scales like h . This is known as a first order approximation of $u'(x)$.

Now let's approximate $u''(x)$. We will once again use Taylor's Theorem, but in a more clever way.

From Taylor's theorem with $k=3$

$$u(x+h) = u(x) + u'(x)h + u''(x)\frac{h^2}{2} + u'''(x)\frac{h^3}{6} + o(h^4)$$

We can also replace h by $-h$ in the above to get

$$u(x-h) = u(x) - u'(x)h + u''(x)\frac{h^2}{2} - u'''(x)\frac{h^3}{6} + O(h^4)$$

Adding these two equations gives us

$$u(x+h) + u(x-h) = 2u(x) + u''(x)h^2 + O(h^4) \rightarrow$$

$$\frac{u(x+h) - 2u(x) + u(x-h)}{h^2} = u''(x) + O(h^2).$$

This says that we can replace $u''(x)$ by

$$\frac{u(x+h) - 2u(x) + u(x-h)}{h^2} \quad \text{and we will only}$$

introduce an error of order h^2 . This is known as a second order approximation to $u''(x)$.

To summarize :

$$u'(x) = \frac{u(x+h) - u(x)}{h} + O(h)$$

$$u''(x) = \frac{u(x+h) - 2u(x) + u(x-h)}{h^2} + O(h^2)$$

Let us substitute these into our ODE:

$$\left[\begin{array}{l} -\rho \left(\frac{u(x+h) - 2u(x) + u(x-h)}{h^2} + O(h^2) \right) + \\ q \left(\frac{u(x+h) - u(x)}{h} + O(h) \right) + r u(x) \end{array} \right] = f(x)$$

The left side can be rewritten as

$$\underbrace{-\frac{\rho}{h^2} u(x-h)}_{:= \alpha} + \underbrace{\left[\frac{2\rho}{h^2} - \frac{q}{h} + r \right] u(x)}_{:= \beta} + \underbrace{\left[\frac{q}{h} - \frac{\rho}{h^2} \right] u(x+h)}_{\substack{:= \gamma \\ (-\rho O(h^2) + q O(h))}} + \underbrace{}_{= O(h)}$$

so that

$$\alpha u(x-h) + \beta u(x) + \gamma u(x+h) + O(h) = f(x) .$$

This says that, for sufficiently small h , our solution

u to our ODE satisfies the equation

$$\alpha u(x-h) + \beta u(x) + \gamma u(x+h) = f(x)$$

up to an approximation error that is of size h .

This is known as the

1st order forward finite difference approximation

to our ODE at the point x .

So far we have shown that if u solves our ODE,

then u approximately satisfies the finite difference

equation at each $a < x < b$. We are now going to

construct a function u_h that solves the finite difference

equation at finitely many points $a < x_1 < x_2 < \dots < x_n < b$

and which also satisfies the boundary conditions

$u_h(a) = g_a$, $u_h(b) = g_b$. This u_h will be a

good approximation of the original solution u .

To start, let $K > 0$ and let $h = \frac{b-a}{2^K}$.

Now let $x_i = a + ih$ for $i = 0, 1, \dots, 2^K$.

Let $u_h : [a, b] \rightarrow \mathbb{R}$ be piecewise linear on each

$[x_i, x_{i+1}]$ and satisfy the finite difference equation

$$\alpha u(x_i - h) + \beta u(x_i) + \gamma u(x_i + h) = f(x_i)$$

for each $i = 1, 2, \dots, 2^k - 1$ as well as the boundary

conditions $u(a) = u(x_0) = g_a$

$$u(b) = u(x_{2^k}) = g_b$$

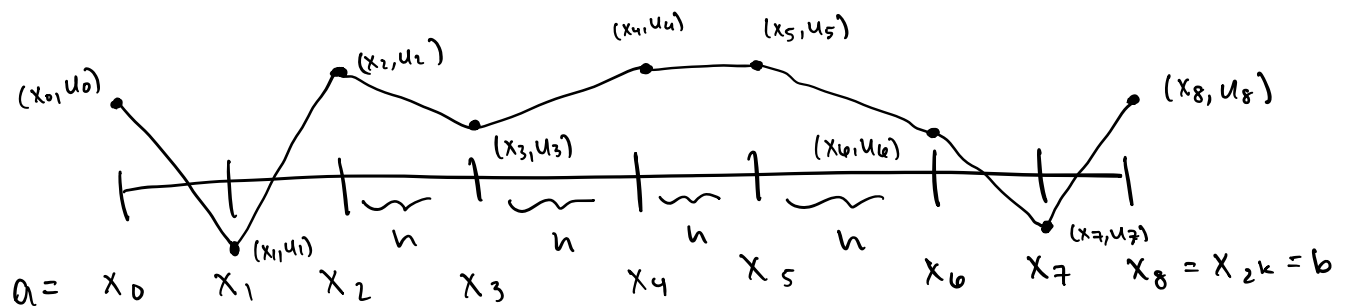
For notation, let $u_i = u(x_i)$ and $f_i = f(x_i)$.

Since $x_i - h = x_{i-1}$ and $x_i + h = x_{i+1}$, we

have the following system of equations:

$$\begin{aligned} u_0 &= g_a \\ \alpha u_0 + \beta u_1 + \gamma u_2 &= f_1 \\ \alpha u_1 + \beta u_2 + \gamma u_3 &= f_2 \\ &\vdots \\ \alpha u_{2^k-2} + \beta u_{2^k-1} + \gamma u_{2^k} &= f_{2^k-1} \\ u_{2^k} &= g_b \end{aligned}$$

There are $2^k + 1$ linear equations in $2^k + 1$ unknowns u_0, u_1, \dots, u_{2^k} . We can solve this system for the u_0, u_1, \dots, u_{2^k} . Since u_h is piecewise linear on each $[x_i, x_{i+1}]$, these $2^k + 1$ values uniquely determine u_h . For example, u_h looks like (here $k=3$)



To Summarize the Finite Difference Method :

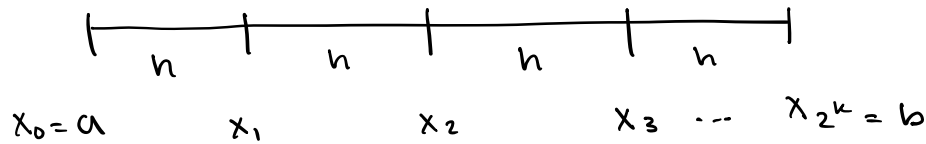
1. Discretize the PDE with finite differences

$$\begin{cases} -\rho u''(x) + q u'(x) + r u(x) = f(x) \\ u(a) = g_a \\ u(b) = g_b \end{cases} \longrightarrow$$

$$\begin{cases} -\rho \left(\frac{u(x+h) - 2u(x) + u(x-h))}{h^2} \right) + q \left(\frac{u(x+h) - u(x)}{h} \right) + r u(x) = f(x) \\ u(a) = g_a \\ u(b) = g_b \end{cases}$$

2. Discretize the domain

$$h = \frac{b-a}{2^k}$$



$$x_i = a + ih \quad i = 0, 1, \dots, 2^k$$

3. Set up linear system

$$\begin{cases} u_0 = g_a \\ -\rho \left(\frac{u_{i+1} - 2u_i + u_{i-1}}{h^2} \right) + q_i \left(\frac{u_{i+1} - u_i}{h} \right) + r u_i = f_i \quad i=1, \dots, 2^k-1 \\ u_{2^k} = g_b \end{cases}$$

$$u_i = u(x_i)$$

$$f_i = f(x_i)$$

4. Solve linear system for u_0, u_1, \dots, u_{2^k}

Remark In step 1, we used a 2nd order

approximation for u'' but only a 1st order

approximation for u' . This reduces the accuracy

of our method to only 1st order. Is there a way to approximate u'' to the second order, thus boosting the accuracy of our method by 1 degree higher? Yes! Here's how.

Start with Taylor's Theorem with $k=2$, h , and $-h$:

$$(1) \quad u(x+h) = u(x) + u'(x)h + u''(x)\frac{h^2}{2} + O(h^3)$$

$$(2) \quad u(x-h) = u(x) - u'(x)h + u''(x)\frac{h^2}{2} + O(h^3)$$

Subtract equation 2 from equation 1:

$$u(x+h) - u(x-h) = 2u'(x)h + O(h^3) \rightarrow$$

$$\frac{u(x+h) - u(x-h)}{2h} = u'(x) + O(h^2)$$

This gives us a 2nd order centered

approximation of $u'(x)$. Replace $u'(x)$

with $\frac{u(x+h) - u(x-h)}{2h}$ in step 1 to get

a 2nd order method. This will modify what your linear system looks like in step 3.

I leave the details to you as an exercise.

Some final remarks:

1. We can also discretize $u'(x)$ via

$$u'(x) = \frac{u(x) - u(x-h)}{h} + O(h)$$

This known as a 1st order backwards difference.

2. In our original ODE

$$-p u''(x) + q u'(x) + r u(x) = f(x)$$

the middle term $q u'(x)$, known as the

advection term, gives rise to some common terminology:

(i) If $q > 0$:

- The forward approximation

$$q u'(x) \approx q \left(\frac{u(x+h) - u(x)}{h} \right) \text{ is}$$

called a downwind approximation,

- The backward approximation

$$q u'(x) \approx q \left(\frac{u(x) - u(x-h)}{h} \right) \text{ is}$$

called an upwind approximation.

(ii) If $q < 0$

- The forward approximation is called an upwind approximation.

- The backward approximation is called a downwind approximation.