

Definition Let K be a polygon (square or triangle),

$P(K)$ a space of polynomials defined on K ,

and Σ a set of linear functionals on $P(K)$, called degrees of freedom.

Then the triple $(K, P(K), \Sigma)$ is unisolvent

if 1. $\#\Sigma = \dim P(K)$

2. For any $p \in P(K)$, if $\sigma(p) = 0$ for all $\sigma \in \Sigma$, then $p = 0$.

Remarks • A member of $P(K)$ is a

polynomial $p: K \rightarrow \mathbb{R}$. For example,

if K is the unit square and $P(K)$ is the space of all degree at most 2 polynomials on

K , then a typical member of $P(K)$ is of

the form $p(x,y) = c_1 + c_2x + c_3y + c_4x^2 + c_5xy + c_6y^2$

for some constants $c_1, c_2, c_3, c_4, c_5, c_6$

- A member of Σ is a linear map $\sigma: P(K) \rightarrow \mathbb{R}$. That is, σ assigns to each polynomial $p \in P(K)$ a real number $\sigma(p) \in \mathbb{R}$, and for any scalar $c \in \mathbb{R}$, any 2 polynomials $p_1, p_2 \in P(K)$

$$\sigma(cp_1 + p_2) = c\sigma(p_1) + \sigma(p_2).$$

For example, if we fix a point $(x_0, y_0) \in K$,

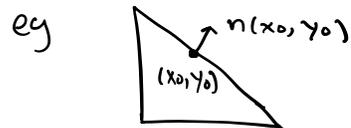
then $\sigma(p) = p(x_0, y_0)$ is a valid degree of freedom.

Other examples include $\sigma(p) = \partial_x p(x_0, y_0)$,

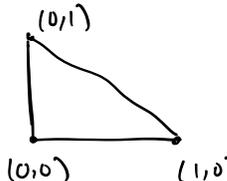
$$\sigma(p) = \int_K p(x, y) dx dy,$$

$$\sigma(p) = \underbrace{\partial_n p(x_0, y_0)}_{\text{normal derivative}} = \nabla p(x_0, y_0) \cdot \underbrace{n(x_0, y_0)}_{\text{outward unit normal}}$$

for (x_0, y_0) on boundary of K



- Condition 1 of unisolvence means that the dimension of the vector space $P(K)$ must be the same as the number of degrees of freedom (DOF's)

For example, w/ $K =$ 

$$P(K) = \underbrace{P_1(K)}_{\text{deg} \leq 1 \text{ polynomials on } K} = \text{span} \{1, x, y\}$$

$$\sigma_1(p) = p(0,0)$$

$$\sigma_i : P(K) \rightarrow \mathbb{R}$$

$$\sigma_2(p) = p(1,0)$$

$$\Sigma = \{ \sigma_1, \sigma_2, \sigma_3 \}$$

$$\sigma_3(p) = p(0,1)$$

$$\text{we have } \dim P(K) = 3 = \# \Sigma$$

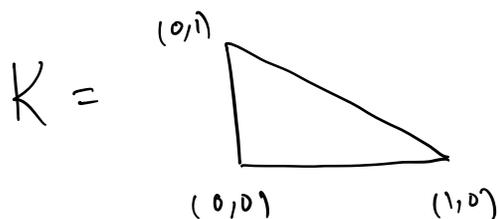
On the other hand, if we keep Σ the

$$\text{same but now take } P(K) = \underbrace{P_2(K)}_{\text{deg} \leq 2 \text{ polynomials}} = \text{span} \{1, x, y, x^2, xy, y^2\}$$

$$\text{we have } \dim P(K) = 6 \neq \# \Sigma = 3$$

- Condition 2 of unisolvence says that the only polynomial that can vanish on / annihilate all of the DOF's is the zero polynomial.

For example,



$$P(K) = P_1(K)$$

$$\sigma_1(p) = p(0,0) \quad \sigma_2(p) = p(1,0) \quad \sigma_3(p) = p(0,1)$$

$$\Sigma = \{ \sigma_1, \sigma_2, \sigma_3 \}$$

claim: $(K, P(K), \Sigma)$ is unisolvent.

proof. $\dim P(K) = 3 = \# \Sigma$

Now let $p \in P(K)$ satisfy

$$\sigma_1(p) = p(0,0) = 0, \quad \sigma_3(p) = p(0,1) = 0.$$

$$\sigma_2(p) = p(1,0) = 0,$$

We will show this implies $p = 0$.

Since $p \in P(K) = \text{span} \{1, x, y\}$,

\exists constants $c_1, c_2, c_3 \in \mathbb{R}$ so

$$p(x, y) = c_1 + c_2 x + c_3 y \quad \forall (x, y) \in K$$

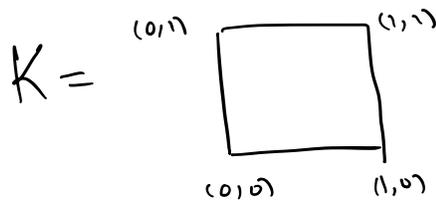
$$\begin{array}{l} \text{Then } p(0, 0) = c_1 = 0 \\ p(1, 0) = c_1 + c_2 = 0 \\ p(0, 1) = c_1 + c_3 = 0 \end{array} \left. \vphantom{\begin{array}{l} p(0, 0) = c_1 = 0 \\ p(1, 0) = c_1 + c_2 = 0 \\ p(0, 1) = c_1 + c_3 = 0 \end{array}} \right\} \rightarrow c_1 = c_2 = c_3 = 0$$

$$\rightarrow p(x, y) = 0 \quad \forall x, y \rightarrow p = 0.$$

Thus conditions 1, 2 are satisfied, so

$(K, P(K), \Sigma)$ is unisolvant. \square

Another example



$$P(K) = P_2(K) = \text{span} \{1, x, y, x^2, y^2, xy\}$$

$$\sigma_1(p) = p(0,0)$$

$$\sigma_4(p) = p(1,1)$$

$$\sigma_2(p) = p(1,0)$$

$$\sigma_5(p) = p(1/2, 1/2)$$

$$\sigma_3(p) = p(0,1)$$

$$\sigma_6(p) = \int_{\mathbb{R}} p(x,y) dx dy$$

claim: $(K, P(K), \Sigma)$ is not unisolvant.

proof. $\dim P(K) = 6 = \# \Sigma$. Now

suppose $p \in P(K)$ satisfies $\sigma_i(p) = 0 \forall i$.

$\exists c_1, c_2, c_3, c_4, c_5, c_6 \in \mathbb{R}$ so

$$\text{Then } p \in P(K) \rightarrow p(x,y) = c_1 + c_2x + c_3y + c_4x^2 + c_5xy + c_6y^2 \quad \forall (x,y) \in K$$

$$\therefore \sigma_1(p) = p(0,0) = c_1 = 0 \quad (1)$$

$$\sigma_2(p) = p(1,0) = c_1 + c_2 + c_4 = 0 \quad (2)$$

$$\sigma_3(p) = p(0,1) = c_1 + c_3 + c_6 = 0 \quad (3)$$

$$\sigma_4(p) = p(1,1) = c_1 + c_2 + c_3 + c_4 + c_5 + c_6 = 0 \quad (4)$$

$$\sigma_5(p) = p(1/2, 1/2) = c_1 + c_2/2 + c_3/2 + c_4/4 + c_5/4 + c_6/4 = 0 \quad (5)$$

$$\sigma_0(p) = \int_K p(x,y) dx dy = \int_0^1 \int_0^1 c_1 + c_2 x + c_3 y + c_4 x^2 + c_5 xy + c_6 y^2 dx dy$$

$$= c_1 + \frac{c_2}{2} + \frac{c_3}{2} + \frac{c_4}{3} + \frac{c_5}{4} + \frac{c_6}{3} = 0$$

(6)

Equations (1) - (6) can be put in

matrix-vector form like

$$\underbrace{\begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 \\ 1 & 1 & 0 & 1 & 0 & 0 \\ 1 & 0 & 1 & 0 & 0 & 1 \\ 1 & 1 & 1 & 1 & 1 & 1 \\ 1 & 1/2 & 1/2 & 1/4 & 1/4 & 1/4 \\ 1 & 1/2 & 1/2 & 1/3 & 1/4 & 1/3 \end{bmatrix}}_A \underbrace{\begin{bmatrix} c_1 \\ c_2 \\ c_3 \\ c_4 \\ c_5 \\ c_6 \end{bmatrix}}_{\vec{c}} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

If $\det A \neq 0$, then A^{-1} exists, so

$$A\vec{c} = 0 \rightarrow A^{-1}A\vec{c} = A^{-1}0 \rightarrow \vec{c} = 0 \rightarrow p = 0$$

\therefore unisolvant!

If $\det A = 0$ then A^{-1} does not exist,

and there must exist some choice of

$c_1, \dots, c_6 \in \mathbb{R}$ w/ some $c_i \neq 0$ so

$$Ac = 0$$

ie $p(x,y) = c_1 + c_2x + c_3y + c_4x^2 + c_5xy + c_6y^2$

is not the zero polynomial but

all $\sigma_i(p) = 0$. Thus condition #2 fails to hold, so (K, P, Σ) is not unisolvent.

Thus (K, P, Σ) is unisolvent $\leftrightarrow \det A \neq 0$.

Use a computer (or do it by hand) to compute $\det A = 0$, so (K, P, Σ) is

Indeed $p(x,y) = x - x^2 - y + y^2$ satisfies not unisolvent.

$$p(0,0) = 0$$

$$p(1,0) = 0$$

$$p(0,1) = 0$$

$$p(1,1) = 0$$

$$p(1/2, 1/2) = 0$$

$$\int_0^1 \int_0^1 x - x^2 - y + y^2 dx dy = 0$$

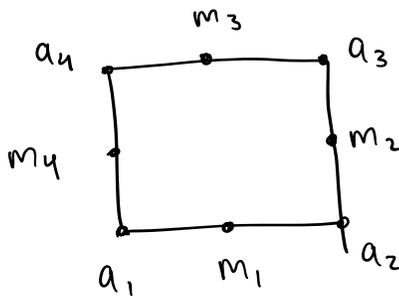
yet $p \neq 0$.

□

DOFS for HW problems

HW 6 Q III

$$\sigma_i(p) = p(m_i)$$



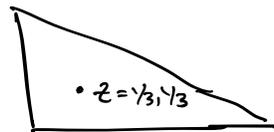
$$\sigma_i(p) = p(a_i)$$

by $\nabla p(a_i)$ we mean $\sigma_i^1(p) = \partial_x p(a_i)$

$$\sigma_i^2(p) = \partial_y p(a_i)$$

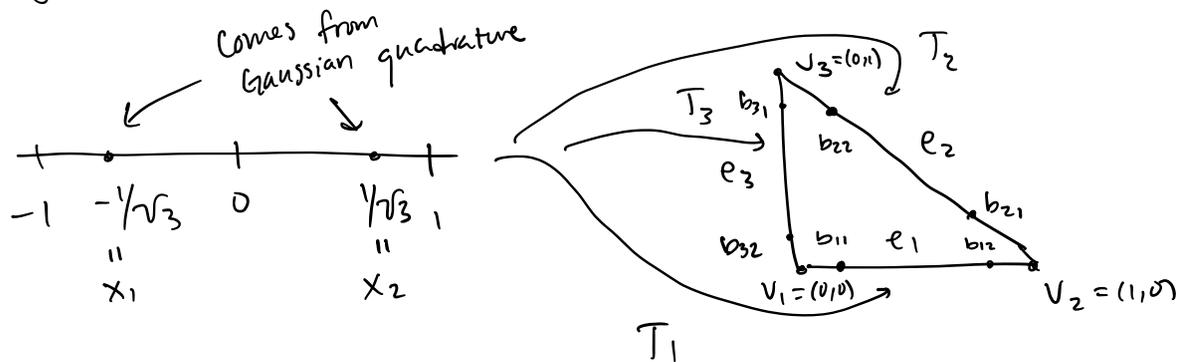
HW 7 Q II

$K =$



$$\sigma_i(p) = p(z)$$

b_{ij} are the Gauss points:



$$b_{ij} = T_i(x_j) \quad \text{where}$$

$$T_1(x) = V_1 \left(\frac{1-x}{2} \right) + V_2 \left(\frac{1+x}{2} \right)$$

$$T_2(x) = V_2 \left(\frac{1-x}{2} \right) + V_3 \left(\frac{1+x}{2} \right)$$

$$T_3(x) = V_3 \left(\frac{1-x}{2} \right) + V_1 \left(\frac{1+x}{2} \right)$$

$$T_i = [-1, 1] \rightarrow e_i \text{ edge of } K$$

by $\nabla^2 p(a_i)$ we mean $\sigma_i^1 = \partial_x^2 p(a_i)$ } 2nd-order
 $\sigma_i^2 = \partial_y^2 p(a_i)$ } derivatives
 $\sigma_i^3 = \partial_x \partial_y p(a_i)$

by $\partial_n p(m_i)$ we mean

$$\sigma_i(p) = \partial_n p(m_i) = \nabla p(m_i) \cdot n(m_i)$$

↙ dot product

