

## 2D Linear FEM Notes

$$\int_{\Omega} (-\Delta u + qu = f) v \quad \int_{\Omega} \nabla \cdot (\nabla u v) = \int_{\Omega} \nabla u \cdot \nabla v + \int_{\Omega} \Delta u v$$

||

$$\int_{\partial\Omega} \nabla u v \cdot n = \int_{\partial\Omega} g v$$

↑  
BC

$$\rightarrow \int_{\Omega} \nabla u \cdot \nabla v - \int_{\partial\Omega} g v + \int_{\Omega} q u v = \int_{\Omega} f v \rightarrow$$

$$a(u, v) := \int_{\Omega} \nabla u \cdot \nabla v + \int_{\Omega} q u v = \int_{\Omega} f v + \int_{\partial\Omega} g v =: F(v)$$

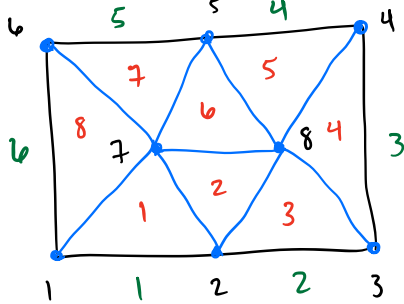
$$u = \sum_i u_i \phi_i$$

$$v = \phi_j \rightarrow \sum_i a(\phi_i, \phi_j) u_i = F(\phi_j)$$

$$\begin{matrix} \left[ a(\phi_i, \phi_j) \right] & \left[ u_i \right] & = & \left[ F(\phi_j) \right] \\ \begin{matrix} j, i \\ \uparrow \uparrow \\ \text{row col} \end{matrix} & \begin{matrix} i \\ \uparrow \\ \text{row} \end{matrix} & & \begin{matrix} j \\ \downarrow \\ \text{row} \end{matrix} \end{matrix}$$

$$a(\phi_i, \phi_j) = \int_{\Omega} \nabla \phi_i \cdot \nabla \phi_j + \int_{\Omega} q \phi_i \phi_j$$

### Enumerating Everything (Example)



1. Enumerate nodes

$$\begin{bmatrix} (x_1, y_1) \\ (x_2, y_2) \\ \vdots \\ (x_8, y_8) \end{bmatrix}$$

2. Enumerate Elements

	k		
k	1	2	7
	2	8	7
	2	3	8
	3	4	8
	4	5	8
	5	7	8
	5	6	7
	1	7	8

← element 1 is composed of nodes 1, 2, and 7 in the nodes list. It's vertices are  $(x_1, y_1)$ ,  $(x_2, y_2)$ ,  $(x_7, y_7)$ .

\* This defines a map  $I(l, m)$

$l$  - element #

$m$  - local vertex # (1, 2, 3)

$I(l, m)$  - global vertex #

3. Enumerate Boundary Edges

	m	
l	1	2
	2	3
	3	4
	4	5
	5	6
	6	1

← edge 1 has vertices  $(x_1, y_1)$  and  $(x_2, y_2)$

\* Defines a map  $J(l, m)$

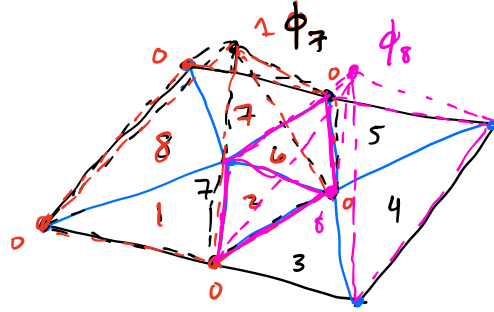
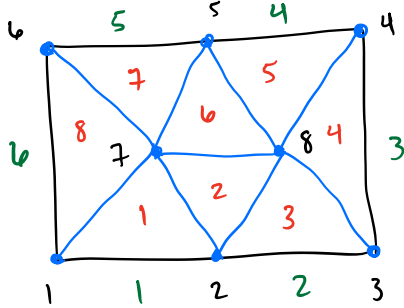
$l$  - edge #

$m$  - local vertex # (1 or 2)

$J(l, m)$  - global vertex #

Element-wise assembly

$$a(\phi_i, \phi_j) = \int_{\Omega} \nabla \phi_i \cdot \nabla \phi_j + \int_{\Omega} q \phi_i \phi_j$$



•  $\text{supp } \phi_i$  is a union of cells

Eg  $\text{supp } \phi_7 = K_1 \cup K_2 \cup K_6 \cup K_7 \cup K_8$

$\text{supp } \phi_8 = K_2 \cup K_3 \cup K_4 \cup K_5 \cup K_6$

•  $\text{supp } \phi_i \cap \text{supp } \phi_j$  is either a set of measure 0 (basically empty for our purposes) or it is a union of cells

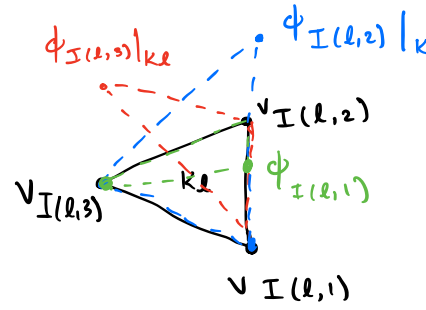
Eg  $\text{supp } \phi_7 \cap \text{supp } \phi_8 = K_2 \cup K_6$

• Therefore,  $a(\phi_i, \phi_j) = 0$  or

$$a(\phi_i, \phi_j) = \sum_{K \in \text{supp } \phi_i \cap \text{supp } \phi_j} \underbrace{\int_K \nabla \phi_i \cdot \nabla \phi_j + \int_K q \phi_i \phi_j}_{:= a_K(\phi_i, \phi_j)}$$

eg  $a(\phi_7, \phi_8) = a_2(\phi_7, \phi_8) + a_6(\phi_7, \phi_8)$ .

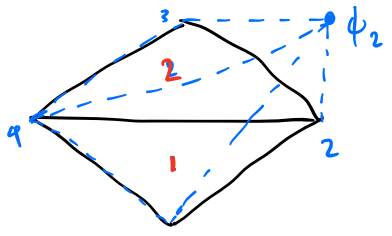
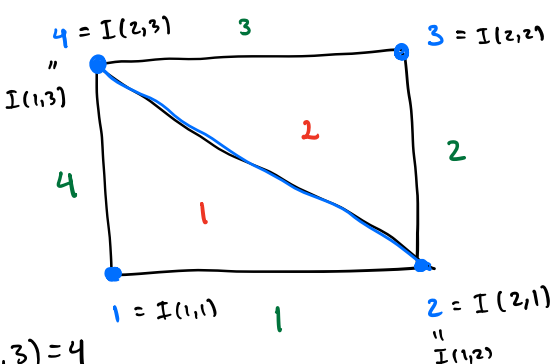
- Calculating  $a(\phi_i, \phi_j)$  involves calculating  $a_\ell(\phi_i, \phi_j)$  where  $\ell$  varies over the element numbers

- Consider this procedure
  - Fix an element  $K_\ell$ 

  - The only basis functions  $\phi_i$  where  $K_\ell \subset \text{supp } \phi_i$  are  $\phi_{I(l,1)}, \phi_{I(l,2)}, \phi_{I(l,3)}$
  - Thus the only  $a_\ell(\phi_i, \phi_j)$  that are not zero are  $a_\ell(\phi_{I(l,m)}, \phi_{I(l,n)})$  for  $m, n = 1, 2, 3$
  - For each  $m, n = 1, 2, 3$  :  
 calculate  $a_\ell(\phi_{I(l,m)}, \phi_{I(l,n)})$  and add it to the entry corresponding to  $a(\phi_{I(l,m)}, \phi_{I(l,n)})$  in  $[\alpha(\phi_i, \phi_j)]_{j,i}$  matrix

Claim: If we do step 4 for each element  $K_\ell$ , then we will have completely assembled the matrix  $[\alpha(\phi_i, \phi_j)]_{j,i}$

Example

- $I(1,1) = 1$
- $I(1,2) = 2$
- $I(1,3) = 4$
- $I(2,1) = 2$
- $I(2,2) = 3$



$$\begin{bmatrix} a(\phi_1, \phi_1) & a(\phi_2, \phi_1) & a(\phi_3, \phi_1) & a(\phi_4, \phi_1) \\ a(\phi_1, \phi_2) & a(\phi_2, \phi_2) & a(\phi_3, \phi_2) & a(\phi_4, \phi_2) \\ a(\phi_1, \phi_3) & a(\phi_2, \phi_3) & a(\phi_3, \phi_3) & a(\phi_4, \phi_3) \\ a(\phi_1, \phi_4) & a(\phi_2, \phi_4) & a(\phi_3, \phi_4) & a(\phi_4, \phi_4) \end{bmatrix}$$

$$\begin{aligned} a(\phi_2, \phi_2) &= a_1(\phi_2, \phi_2) + a_2(\phi_2, \phi_2) \\ &= a_1(\phi_{I(1,2)}, \phi_{I(1,2)}) + a_2(\phi_{I(2,1)}, \phi_{I(2,1)}) \end{aligned}$$

$$\begin{bmatrix} a_1(\phi_1, \phi_1) & a_1(\phi_2, \phi_1) & 0 & a_1(\phi_4, \phi_1) \\ a_1(\phi_1, \phi_2) & a_1(\phi_2, \phi_2) & 0 & a_1(\phi_4, \phi_2) \\ 0 & 0 & 0 & 0 \\ a_1(\phi_1, \phi_4) & a_1(\phi_2, \phi_4) & 0 & a_1(\phi_4, \phi_4) \\ 0 & 0 & 0 & 0 \end{bmatrix} +$$

$$\begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & a_2(\phi_2, \phi_2) & a_2(\phi_3, \phi_2) & a_2(\phi_4, \phi_2) \\ 0 & a_2(\phi_2, \phi_3) & a_2(\phi_3, \phi_3) & a_2(\phi_4, \phi_3) \\ 0 & a_2(\phi_2, \phi_4) & a_2(\phi_3, \phi_4) & a_2(\phi_4, \phi_4) \end{bmatrix}$$

Calculating  $a_l(\phi_{I(l,m)}, \phi_{I(l,n)})$  :

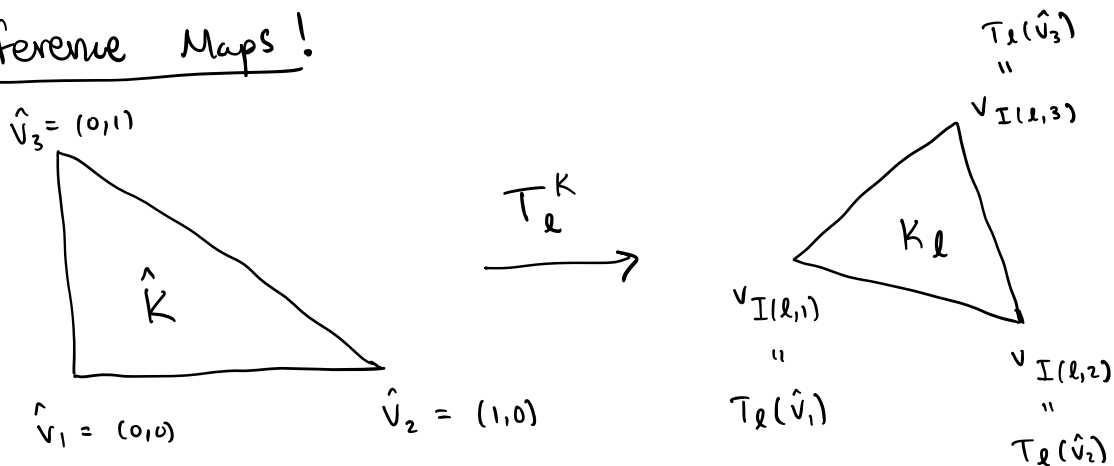
$$a_l(\phi_{I(l,m)}, \phi_{I(l,n)}) = \int_{K_l} \nabla \phi_{I(l,m)} \cdot \nabla \phi_{I(l,n)} dx +$$

:=  $S(l,m,n)$  stiffness term

$$\int_{K_l} \rho \phi_{I(l,m)} \phi_{I(l,n)} dx$$

:=  $M(l,m,n)$  mass term

Reference Maps!



$$T_l^K(\hat{x}) := v_{I(l,1)} + (v_{I(l,2)} - v_{I(l,1)}) \hat{x}_1 + (v_{I(l,3)} - v_{I(l,1)}) \hat{x}_2$$

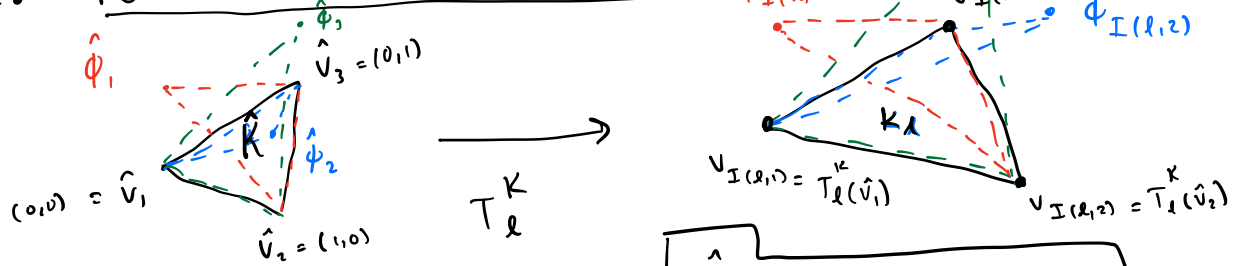
$$= v_{I(l,1)} + \begin{bmatrix} v_{I(l,2)} - v_{I(l,1)} & v_{I(l,3)} - v_{I(l,1)} \end{bmatrix} \begin{bmatrix} \hat{x}_1 \\ \hat{x}_2 \end{bmatrix}$$

matrix w/ columns :=  $B_l$

Facts about  $T_\ell^K$  : 1.  $DT_\ell^K = B_\ell$

Jacobian matrix

2. Reference basis functions on  $\hat{K}$



$$\textcircled{*} \phi_{I(l,m)} \circ T_\ell^K = \hat{\phi}_m^K \quad m=1,2,3$$

$$\begin{aligned} \hat{\phi}_1^K(\hat{x}) &= 1 - \hat{x}_1 - \hat{x}_2 \\ \hat{\phi}_2^K(\hat{x}) &= \hat{x}_1 \\ \hat{\phi}_3^K(\hat{x}) &= \hat{x}_2 \end{aligned}$$

$$M(l,m,n) = \int_{K_\ell} q(x) \phi_{I(l,m)}(x) \phi_{I(l,n)}(x) dx$$

Change variables  
 $x = T_\ell^K(\hat{x}) \rightarrow =$

comes from  
 changing  
 variables in  
 multiple  
 dimensions

$$\int_{\hat{K}} q \circ T_\ell^K(\hat{x}) \cdot \underbrace{\phi_{I(l,m)} \circ T_\ell^K(\hat{x})}_{\hat{\phi}_m^K(\hat{x})} \cdot \underbrace{\phi_{I(l,n)} \circ T_\ell^K(\hat{x})}_{\hat{\phi}_n^K(\hat{x})} \cdot |\det DT_\ell^K| d\hat{x}$$

$$M(l,m,n) = |\det B_\ell| \int_{\hat{K}} q \circ T_\ell^K \hat{\phi}_m^K \hat{\phi}_n^K d\hat{x}$$

much simpler  
 to calculate!

$$S(l,m,n) = \int_K \nabla_x \phi_{I(l,m)}(x) \cdot \nabla_x \phi_{I(l,n)}(x) dx$$

$$= \int_{\hat{K}} (\nabla_x \phi_{I(l,m)}) \circ T_l^K(\hat{x}) \cdot (\nabla_x \phi_{I(l,m)}) \circ T_l^K(\hat{x}) |\det DT_l^K| d\hat{x}$$

change variables  $x = T_l^K(\hat{x})$

Chain rule:

$$\begin{aligned} \nabla_{\hat{x}} (\underbrace{\phi_{I(l,m)} \circ T_l^K}_{\hat{\phi}_m})(\hat{x}) &= (\nabla_x \phi_{I(l,m)}) \circ T_l^K(\hat{x}) DT_l^K \\ \uparrow \text{gradient wrt } \hat{x} \text{ variables} & \quad \uparrow \text{gradient wrt } x \text{ variables} \\ &= (\nabla_x \phi_{I(l,m)}) \circ T_l^K(\hat{x}) B_l \end{aligned}$$

$$\rightarrow \boxed{\nabla_{\hat{x}} \hat{\phi}_m^K(\hat{x}) B_l^{-1} = (\nabla_x \phi_{I(l,m)}) \circ T_l^K(\hat{x}) \quad m=1,2,3}$$

$$S(l,m,n) = |\det B_l| \int_{\hat{K}} (\underbrace{\nabla_{\hat{x}} \hat{\phi}_m^K(\hat{x}) B_l^{-1}}_{\text{row vector}}) \cdot (\underbrace{\nabla_{\hat{x}} \hat{\phi}_n^K(\hat{x}) B_l^{-1}}_{\text{matrix}}) d\hat{x}$$

dot product of 2 vectors

$$\begin{aligned} \nabla_{\hat{x}} \hat{\phi}_1^K &= (-1, -1) \\ \nabla_{\hat{x}} \hat{\phi}_2^K &= (1, 0) \quad \text{constant!} \\ \nabla_{\hat{x}} \hat{\phi}_3^K &= (0, 1) \end{aligned}$$

$$S(l,m,n) = |\det B_l| \underbrace{\text{area}(\hat{K})}_{\frac{1}{2}} (\nabla \hat{\phi}_m^K B_l^{-1}) \cdot (\nabla \hat{\phi}_n^K B_l^{-1})$$

$$\boxed{S(l,m,n) = \frac{|\det B_l|}{2} (\nabla \hat{\phi}_m^K B_l^{-1}) \cdot (\nabla \hat{\phi}_n^K B_l^{-1})}$$

No integral needed!



# Approximate Integrals w/ Quadrature Rules

Quadrature on reference triangle idea

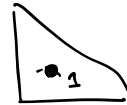
$$f: \hat{K} \rightarrow \mathbb{R}, \quad \hat{x}_1^k, \dots, \hat{x}_n^k \in \hat{K}, \quad \hat{w}_1^k, \dots, \hat{w}_n^k \in \mathbb{R}$$

$$\int_{\hat{K}} f(\hat{x}) d\hat{x} \approx \text{area}(\hat{K}) \sum_{i=1}^n \hat{w}_i^k f(\hat{x}_i^k) = \frac{1}{2} \sum_{i=1}^n \hat{w}_i^k f(\hat{x}_i^k)$$

Some good choices for  $\{\hat{x}_i^k\}$ ,  $\{\hat{w}_i^k\}$ :

① Centroid, exact for when  $f$  is degree 1 or less

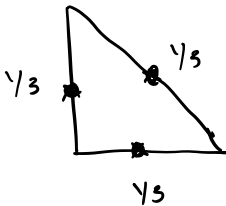
$$n=1, \quad \hat{x}_1^k = (1/3, 1/3), \quad \hat{w}_1^k = 1$$



② midpoint, exact for when  $f$  is degree 2 or less

$$n=3 \quad \hat{x}_1^k = (1/2, 0), \quad \hat{x}_2^k = (1/2, 1/2), \quad \hat{x}_3^k = (0, 1/2)$$

$$\hat{w}_1^k = \hat{w}_2^k = \hat{w}_3^k = 1/3$$



Can find higher order quadrature rules online.

$$M(l, m, n) \approx \frac{|\det B_\ell|}{2} \sum_i \hat{w}_i^k g_\ell(T_\ell(\hat{x}_i^k)) \hat{\phi}_m^k(\hat{x}_i^k) \hat{\phi}_n^k(\hat{x}_i^k)$$

Altogether:

$S(l, m, n)$

$$a_\alpha(\phi_{I(l,m)}, \phi_{I(l,m)}) \approx \frac{|\det B_\alpha|}{2} (\nabla \hat{\phi}_m^K B_\alpha^{-1}) \cdot (\nabla \hat{\phi}_n^K B_\alpha^{-1}) +$$

$$\frac{|\det B_\alpha|}{2} \sum_{i=1}^{\text{number quadrature points}} \hat{w}_i^K q(T_\alpha^K(\hat{x}_i^K)) \hat{\phi}_m^K(\hat{x}_i^K) \hat{\phi}_n^K(\hat{x}_i^K)$$

Computable!

$$\approx M(l, m, n).$$

We can now assemble the matrix  $[a(\phi_i, \phi_j)]_{j,i}$ .

$$F(\phi_j) = \underbrace{\int_\Omega f \phi_j}_{F_\Omega(\phi_j)} + \underbrace{\int_{\partial\Omega} g \phi_j}_{F_{\partial\Omega}(\phi_j)} \rightarrow$$

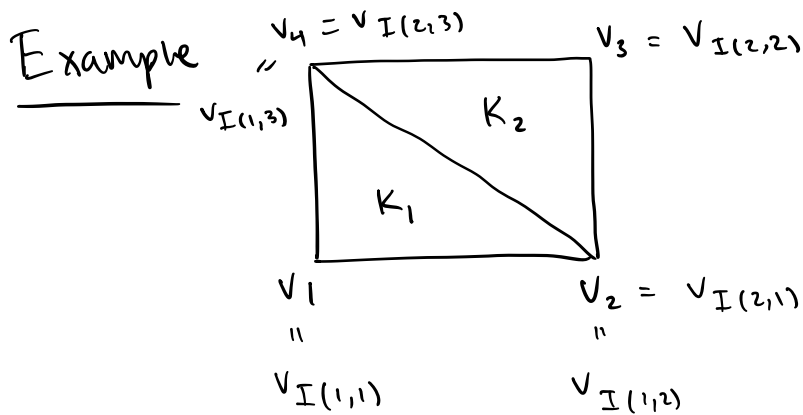
$$[F(\phi_j)]_j = [F_\Omega(\phi_j)]_j + [F_{\partial\Omega}(\phi_j)]_j$$

Assembling  $[F_\Omega(\phi_j)]$  is similar to  $[a(\phi_i, \phi_j)]_{j,i}$

$$F_\Omega(\phi_j) = \sum_{K_\alpha \subset \text{supp } \phi_j} \underbrace{\int_{K_\alpha} f \phi_j}_{:= F_{\Omega,\alpha}(\phi_j)} \rightarrow$$

For each element  $K_l$ , calculate

$\int_{K_l} f \phi_{I(l,m)}$  and add it to the entry corresponding to  $F_{\Omega}(\phi_{I(l,m)})$  in  $[F(\phi_j)]_j$



$$\begin{bmatrix} F_{\Omega}(\phi_1) \\ F_{\Omega}(\phi_2) \\ F_{\Omega}(\phi_3) \\ F_{\Omega}(\phi_4) \end{bmatrix} = \begin{bmatrix} F_{\Omega,1}(\phi_{I(1,1)}) \\ F_{\Omega,1}(\phi_{I(1,2)}) \\ 0 \\ F_{\Omega,1}(\phi_{I(1,3)}) \end{bmatrix} + \begin{bmatrix} 0 \\ F_{\Omega,2}(\phi_{I(2,1)}) \\ F_{\Omega,2}(\phi_{I(2,2)}) \\ F_{\Omega,2}(\phi_{I(2,3)}) \end{bmatrix}$$

Calculating  $F_{\Omega,l}(\phi_{I(l,m)})$ :

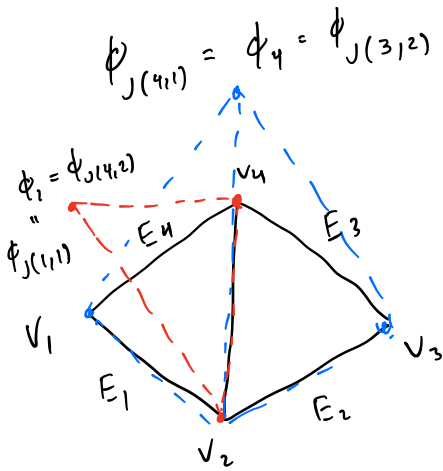
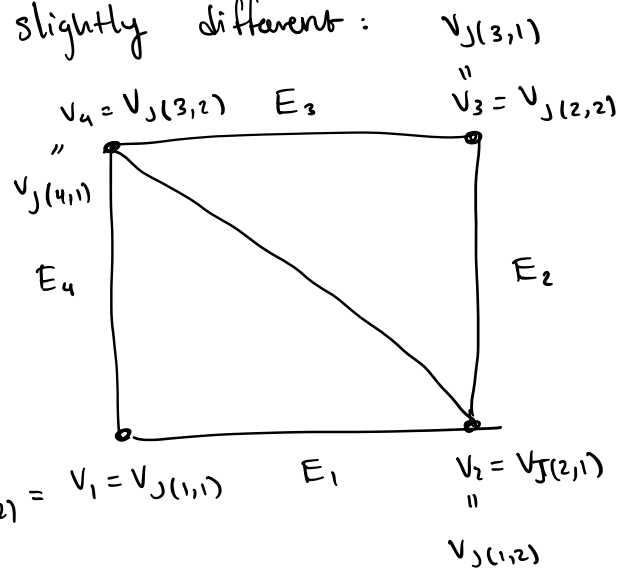
$$\int_{K_l} f \phi_{I(l,m)} dx = \int_{\hat{K}} f \circ T_l^K \hat{\phi}_m^K |det DT_l^K| d\hat{x}$$

$$= |det B_l| \int_{\hat{K}} f \circ T_l^K \hat{\phi}_m^K \approx \frac{|det B_l|}{2} \sum_{\hat{i}=1}^{\# \text{quad pts}} \hat{w}_i^K f(T_l^K(\hat{x}_i^K)) \hat{\phi}_m^K(\hat{x}_i^K)$$

Assembling  $[F_{\partial\Omega}(\phi_j)]_j$  is slightly different:

$$F_{\partial\Omega}(\phi_j) = \int_{\partial\Omega} g \phi_j$$

Example



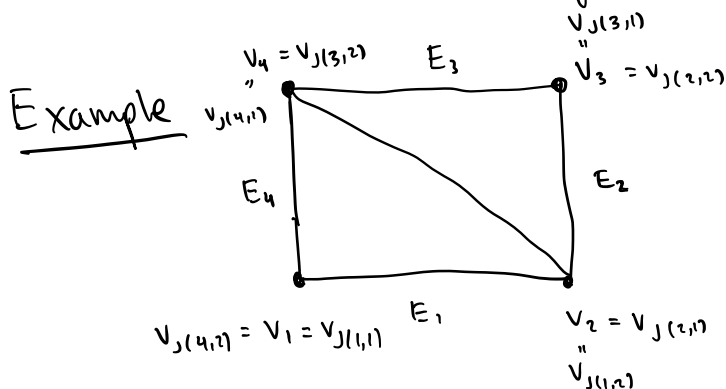
$$F_{\partial\Omega}(\phi_j) = \sum_{E_l \subset \text{supp } \phi_j} \int_{E_l} g \phi_j$$

$F_{\partial\Omega, l}(\phi_j)$

The only nonzero  $F_{\partial\Omega, l}(\phi_j)$  are  $F_{\partial\Omega, l}(\phi_{J(l, m)})$   $m=1, 2$ .

Thus for each edge  $E_l$ , if we calculate  $F_{\partial\Omega, l}(\phi_{J(l, m)})$  and add it to the corresponding entry in  $[F_{\partial\Omega}(\phi_j)]_j$

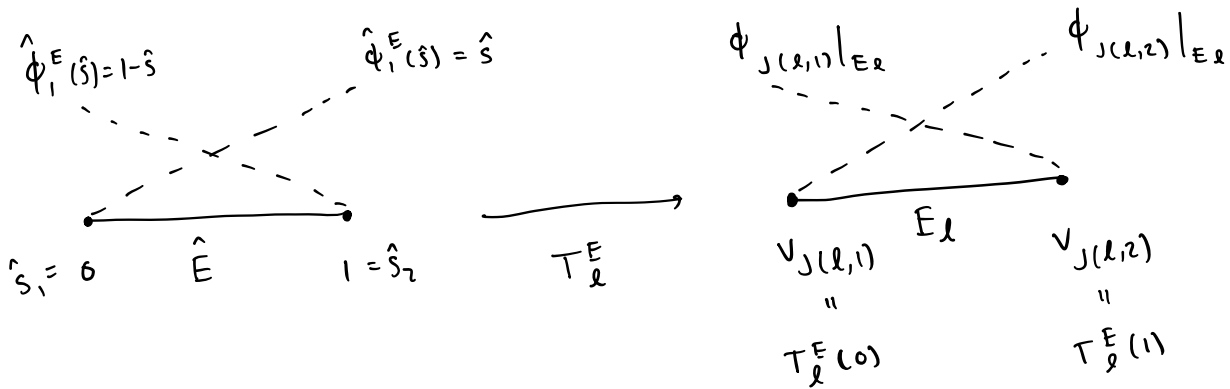
then we will have completely assembled  $[F_{\partial\Omega}(\phi_j)]_j$



$$\begin{bmatrix} F_{\partial\Omega}(\phi_1) \\ F_{\partial\Omega}(\phi_2) \\ F_{\partial\Omega}(\phi_3) \\ F_{\partial\Omega}(\phi_4) \end{bmatrix} = \begin{bmatrix} F_{\partial\Omega,1}(\phi_{J(1,1)}) \\ F_{\partial\Omega,1}(\phi_{J(1,2)}) \\ 0 \\ 0 \end{bmatrix} + \begin{bmatrix} 0 \\ F_{\partial\Omega,2}(\phi_{J(2,1)}) \\ F_{\partial\Omega,2}(\phi_{J(2,2)}) \\ 0 \end{bmatrix} + \\
 \begin{bmatrix} 0 \\ 0 \\ F_{\partial\Omega,3}(\phi_{J(3,1)}) \\ F_{\partial\Omega,3}(\phi_{J(3,2)}) \end{bmatrix} + \begin{bmatrix} F_{\partial\Omega,4}(\phi_{J(4,2)}) \\ 0 \\ 0 \\ F_{\partial\Omega,4}(\phi_{J(4,1)}) \end{bmatrix}$$

Calculating  $F_{\partial\Omega, \ell}(\phi_{J(\ell, m)})$ :

Need reference maps for edges!



$$T_\ell^E(\hat{s}) = v_{J(\ell,1)} + (v_{J(\ell,2)} - v_{J(\ell,1)})\hat{s} \rightarrow \frac{d}{d\hat{s}} T_\ell^E(\hat{s}) = \underbrace{v_{J(\ell,2)} - v_{J(\ell,1)}}_{\text{is a constant vector!}}$$

$$\phi_{J(\ell, m)}|_{E_\ell} \circ T_\ell^E(\hat{s}) = \hat{\phi}_m^E(\hat{s}) \quad m=1, 2$$

$$F_{\partial R, \ell}(\phi_{J(\ell, m)}) = \int_{E_\ell} g \phi_{J(\ell, m)} ds$$

$$s = T_\ell^E(\hat{s}) \longrightarrow = \int_{\hat{E}} g \circ T_\ell^E \hat{\phi}_m^E \underbrace{\left| \frac{d}{d\hat{s}} T_\ell^E(\hat{s}) \right|}_{\text{Euclidean norm of this 2-vector. Comes from changing variables in multiple dimensions.}} d\hat{s}$$

Euclidean norm of this 2-vector. Comes from changing variables in multiple dimensions.

$$= |V_{J(\ell, 2)} - V_{J(\ell, 1)}| \int_{\hat{E}} g \circ T_\ell^E \hat{\phi}_m^E d\hat{s}$$

Need 1D quadrature rules

to approximate this

Good 1D quadrature rules: (Gauss Quadrature)

$$\int_0^1 f(x) dx \approx \frac{1}{2} \sum_{i=1}^{\#qP} \hat{w}_i^E f\left(\frac{1}{2} \hat{x}_i^E + \frac{1}{2}\right)$$

1.  $\#qP = 1$ ,  $\hat{x}_1^E = 0$ ,  $\hat{w}_1^E = 2$ . Exact for  $f$  a  $\text{deg} \leq 1$  poly.

2.  $\#qP = 2$ ,  $\hat{x}_1^E = -\frac{1}{\sqrt{3}}$ ,  $\hat{x}_2^E = \frac{1}{\sqrt{3}}$ ,  $\hat{w}_1^E = \hat{w}_2^E = 1$   
Exact for degree  $\leq 3$  polynomials.

Can find higher order rules online.

Thus  $F_{\partial x, l}(\phi_{j(l, m)}) \approx$

$$\frac{|V_{j(l, 2)} - V_{j(l, 1)}|}{2} \sum_{i=1}^{\# \text{GP}} \hat{w}_i^E g(T_l^E(\frac{1}{2} \hat{x}_i^E + \frac{1}{2})) \hat{\phi}_m^E(\frac{1}{2} \hat{x}_i^E + \frac{1}{2})$$

We can now completely assemble our system

$$\left[ a(\phi_i, \phi_j) \right]_{j,i} \left[ u_i \right]_i = \left[ F_{\partial^2}(\phi_j) \right]_j + \left[ F_{\partial x}(\phi_j) \right]_j$$

and solve for  $[u_i]_i$ .