

HW 4

1. Show $\exists C$ st when h small

$$\max_i |u_i^h| \leq \underline{C} \|f\|_\infty$$

In the hint, consider

$$\frac{-v_{i+1}^h - 2v_i^h + v_{i-1}^h}{h^2} + b \frac{v_{i+1}^h - v_i^h}{h} = 1$$

$$\Rightarrow \max_i |u_i^h| \leq \underbrace{\left(\max_i v_i^h \right)}_{\text{still depends on } h!} \|f\|_\infty$$

still depends on $h!$

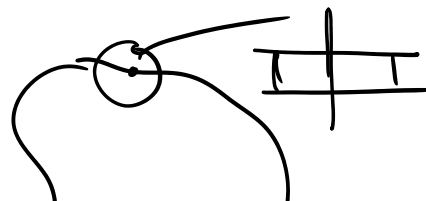
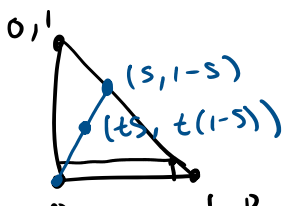
To finish, show $\exists C$ st when h is small

$$\max_i v_i^h \leq C$$

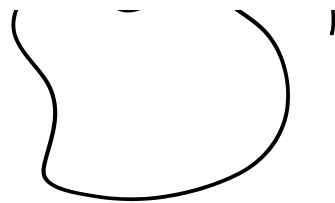
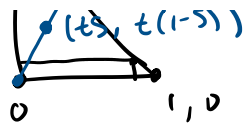
Possible to do, but a little painful.

2.

$K =$

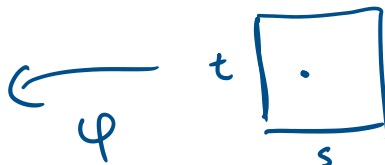
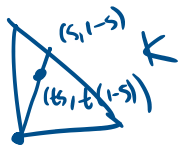


"



$$\varphi(s,t) = (ts, t(1-s))$$

parameterizes K with $Q = [0,1]^2$



$$\int_K f(x,y) dx dy = \int_0^1 \int_0^1 f(\varphi(s,t)) \underbrace{|\det D\varphi(s,t)|}_{t} ds dt$$

\uparrow
 $(x,y) = \varphi(s,t)$

$$\det D\varphi(s,t) = \det \begin{pmatrix} t & s \\ -t & 1-s \end{pmatrix} = \det \begin{pmatrix} t & s \\ 0 & 1 \end{pmatrix} = t$$

Idea: realize

$$\underbrace{\int_0^1 v(s, 1-s)^2 ds}_{\|v\|_{L^2(e)}^2} = \int_0^1 \int_0^1 \frac{d}{dt} \left(t^2 v(\underbrace{ts, t(1-s)}_{\varphi(s,t)})^2 \right) dt ds$$

$$= \int_0^1 \int_0^1 2t v(ts, t(1-s)) \frac{d}{ds} ds + \int_0^1 \int_0^1 t^2 2v(ts, t(1-s)) \cdot \underbrace{\varphi(s,t)}_{(ts, t(1-s))} \cdot \underbrace{\{ \nabla v(\varphi(s,t)) \cdot \}_{dt ds}}_{dt ds}$$

$$2 \|v\|_{L^2(K)}^2 + 2 \int_K v(x,y) (\nabla v(x,y) \cdot (x,y)) dx dy$$

C-S ...

HW5 P1

V, W vs.

$$V \times W = \{ (v,w) \mid v \in V, w \in W \}$$

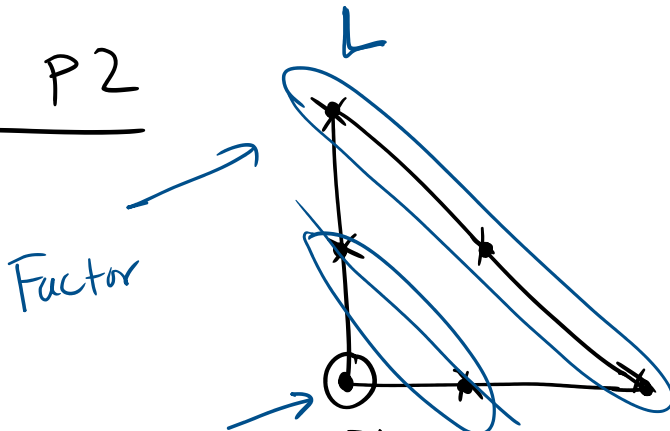
$$\alpha(v_1, w_1) + \alpha(v_2, w_2) = \alpha(v_1 + v_2, w_1 + w_2)$$

$$\alpha : \underbrace{(V \times W)}_X \times \underbrace{(V \times W)}_{X \ni x=(v,w)} \rightarrow \mathbb{R} \quad \text{bilinear}$$

$$\alpha \left(\underbrace{(v_1, w_1)}_{\substack{\uparrow \\ \text{fix one}}}, \underbrace{\alpha(v_2, w_2) + (v_3, w_3)}_{\substack{\uparrow \\ \text{linear in other}}} \right) = \alpha((v_1, w_1), (v_2, w_2)) + \alpha((v_1, w_1), (v_3, w_3))$$

and vice-versa

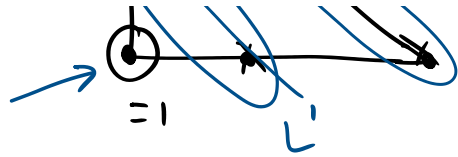
HW5 P2



$$\varphi_i \in \mathbb{TP}^2 \text{ so}$$

$$\sigma_j(\varphi_i) = \delta_{ij}$$

↕



↓

$$\varphi_i(\text{point}) = 1$$

$$\varphi_i(\text{other points}) = 0$$

$$\varphi_i = L(x, y)$$

$$\varphi_i \rightarrow = 0 \text{ at } 2 \text{ pts on } L'$$

d ↑
 $= 0$ on 2 points on L'
 $\neq 0$ on L'

$$\text{deg} \leq 1$$

$$\rightarrow \varphi_i = 0 \text{ on } L'$$

↓ Factor!

$$\varphi_i = L'(x, y) C$$

$$\varphi_i = L(x, y) L'(x, y) C \leftarrow$$